

# ZM2371/ZM2372 SPECIFICATIONS

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**Supplementary value:** This value implies supplementary data of the product and it does not guarantee the product performance.

## 1.1 Specifications

### ■ Measurement

parameters	Z ,  Y , L, C, R, G
parameters	For equivalent circuit of L, C, and R, Parallel / Series / Auto Selection are selectable.
• Secondary parameters	Q, D, $\theta$ , X, B, Rs, Rp, G, Lp, Rdc (direct-current resistance)
• Auto parameter selection	Primary parameters (including equivalent circuit) and secondary parameters can be selected automatically.

### ■ Measured value display range

•  Z	0.000m $\Omega$ to 999.999M $\Omega$
• R (Rs, Rp, Rdc), X	0 $\Omega$ , $\pm$ (0.001m $\Omega$ to 999.999M $\Omega$ )
•  Y	0.00nS to 9.99999kS
• G, B	0S, $\pm$ (0.01nS to 9.99999kS)
• C (Cp, Cs)	0F, $\pm$ (0.00001pF to 999.999kF) ex. 0.000pF to 999.999mF (1kHz) 0.00pF to 9.99999F (120Hz)
• L (Ls, Lp)	0H, $\pm$ (0.001nH to 99.9999GH) ex. 0.0000 $\mu$ H to 99.9999kH (1kHz)
• Q, D	0, $\pm$ (0.00001 to 99999.9)
• $\theta$	$\pm$ 180.000°

Actual measurement and display ranges of respective parameters are restricted by the measurement range or frequency.

### ■ Measurement conditions

• Measurement frequency	1mHz to 100kHz, Resolution 5 digits (1mHz when < 10Hz), $\pm$ 0.01%
• Measurement signal level	10mV to 5.00V, Resolution 3 digits (1mV when < 100mV), $\pm$ (10% + 5mV) RMS value when output is open
• ALC	Constant voltage drive / Constant current drive / Invalid Voltage setting range 10mV to 5.00V, Setting resolution 3 digits (1mV when < 100mV) Current setting range 1 $\mu$ A to 200mA, Setting resolution 3 digits (0.1 $\mu$ A when < 10 $\mu$ A) The constant control range will be narrower than the above specifications depending on the product dispersion or DUT's impedance. The current range is restricted depending on the measurement range.
• Output impedance	5 $\Omega$ / 25 $\Omega$ / 100 $\Omega$ (supplementary values). Automatically selected according to the measurement range. Minimum output impedance restriction function is available. 5 $\Omega$ is selected automatically only when the following conditions are satisfied: Minimum output impedance setting = 5 $\Omega$ , Measurement range $\leq$ 10 $\Omega$ , Measurement signal level $\leq$ 1V, ALC = invalid, Internal DC bias = Off, Secondary parameter $\neq$ Rdc
• Internal DC bias	0V to +2.50V, Resolution 0.01V, $\pm$ (5% + 3mV) when output is open On/Off is possible

## 1.1 Specifications

- Trigger source  
 INT Internal (automatic continuous trigger)  
 MAN Manual  
 EXT Handler interface  
 BUS Remote control
- Trigger delay time  
 Setting range 0.000s to 999.999s, Resolution 0.001s  
 (Time after input of trigger until start of signal acquisition)
- Triggered drive  
 Drive only at measurement / Continuous drive selectable  
 (Measurement signal can be output only during the time from trigger to completion of signal acquisition)
- Measurement speed  
 RAPid / FAST / MEDium / SLOW / VerySLOW

Typical measurement time  
 (Supplementary value. Time from input of trigger to output of measurement end signal EOM)

Measurement frequency	RAP	FAST	MED	SLOW	VSLO
120Hz	10ms	10ms	26ms	126ms	501ms
1kHz	2ms	5ms	25ms	121ms	501ms
10kHz	3ms	5ms	25ms	122ms	502ms
100kHz	3ms	5ms	25ms	122ms	502ms

Conditions: Measurement range fixed, Trigger delay time = 0,  
 Averaging count = 1, Secondary parameter≠Rdc

Signal acquisition time is the value subtracted by about 1ms from the above value.

DUT can be replaced immediately after the completion of signal acquisition. After replacement of DUT, the signal settling time is required additionally.

Additional time when measuring direct-current resistance Rdc (supplementary value)

	RAP	FAST	MED	SLOW	VSLO
(DC)	148ms	148ms	148ms	215ms	613ms

Conditions: DC resistance measurement range fixed,  
 Trigger delay time = 0, Averaging count = 1

- Measurement range

Measurement range	Recommended range	Measurable range
1MΩ	1MΩ to 11MΩ	≥ 900kΩ
100kΩ	100kΩ to 1.1MΩ	≥ 90kΩ
10kΩ	10kΩ to 110kΩ	≥ 9kΩ
1kΩ	1kΩ to 11kΩ	≥ 0.9kΩ
100Ω	9Ω to 1.1kΩ	No limitation
10Ω	0.9Ω to 10Ω	≤ 11Ω
1Ω	90mΩ to 1Ω	≤ 1.1Ω
100mΩ	9mΩ to 100mΩ	≤ 110mΩ

Measurable range: Approximate range in which measurement and display are possible (supplementary value).

Recommended range: Recommended operating range for high accuracy measurement.

Limitation of measurement range

When frequency > 20kHz, 1MΩ range cannot be used.

When minimum output impedance setting is 100Ω, 1Ω range or 100mΩ range cannot be used.

- Measurement range selection  
 Auto / Manual

## ■ Measurement accuracy

- Basic accuracy 0.08%

- Impedance measurement accuracy

Z<sub>r</sub>: Measurement range (100mΩ to 1MΩ)

Z<sub>x</sub>: Measured value of impedance magnitude |Z|

With the above definition, the impedance measurement accuracy is obtained as follows:

Accuracy of impedance magnitude |Z| ±A<sub>z</sub> [%]

$$A_z = (A + B \times U + K_z + K_y) \times V \times K_T + K_B \times U$$

Accuracy of phase angle θ of impedance ±P<sub>z</sub> [°]

$$P_z = 0.573 \times A_z$$

The measurement accuracy when A<sub>z</sub> exceeds 10 [%] is a supplementary value.

Unless otherwise noted, the measurement accuracy of the measured value smaller than half the lower limit of each recommended measurement range or larger than twice the upper limit is a supplementary value.

Each parameter value in the expression is listed below.

- U: Ratio coefficient

Z <sub>x</sub>	U
> 100Ω	Z <sub>x</sub> / Z <sub>r</sub> (however, 1 when Z <sub>x</sub> / Z <sub>r</sub> < 1)
≤ 100Ω	Z <sub>r</sub> / Z <sub>x</sub> (however, 1 when Z <sub>r</sub> / Z <sub>x</sub> < 1)

- V: Signal level coefficient

Measurement signal level [Vrms]	V														
	Zr = 1MΩ, 100kΩ (> 20kHz)			Zr = 100kΩ (≤20kHz), 10kΩ, 1kΩ, 100Ω)			Zr = 10Ω, 1Ω			Zr = 100mΩ					
2 < Level ≤ 5	1.3	1.3	1.3	1.3	1.3	1.3	1.3	1.3	1.3	3	2	1.3			
1 < Level ≤ 2	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.2	1.8	1.5	1.2			
1	1	1	1	1	1	1	1	1	1	1	1	1			
0.5 < Level < 1	1.4	1.2	1.2	1.4	1.2	1.2	1.5	1.5	1.2	2.5	2	1.2			
0.2 < Level ≤ 0.5	1.4	1.3	1.3	1.4	1.3	1.3	2.5	2.2	1.3	3 3 1.3 × ( 0.5Vrms / Meas. signal level [Vrms] )					
0.1 < Level ≤ 0.2	2.2	2.2	1.4	1.4	1.4	1.4	3.5	3.5	1.4						
0.05 < Level ≤ 0.1	2.5	2.5	1.6	1.8	1.6	1.6	× ( 0.2Vrms / Meas. signal level [Vrms] )								
0.02 < Level ≤ 0.05	× ( 0.1Vrms / Meas. signal level [Vrms] )			4	2.8	2									
0.01 ≤ Level ≤ 0.02	level [Vrms] )			8	5	3									

Three coefficients in each column are applied to the measurement speeds RAP, FAST, MED from the left in order.

The coefficient for measurement speeds SLOW and VSLO is same as MED.

For FAST, the coefficient of MED is applied when measurement frequency ≤ 40Hz.

For RAP, the coefficient of FAST when measurement frequency ≤ 250Hz, or that of MED when measurement frequency ≤ 40Hz is applied.

The coefficient varies depending on the frequency when measurement range Z<sub>r</sub> = 100kΩ. At all times, V = 1 for the direct-current resistance Rdc.

• **K<sub>z</sub>: Residual impedance coefficient**

Frequency	K <sub>z</sub> [%]
DC (0Hz), Frequency ≤ 120Hz	$(0.003 + K_c) / Z_x[\Omega]$
120Hz < Frequency ≤ 1kHz	$(0.005 + K_c) / Z_x[\Omega]$
1kHz < Frequency ≤ 10kHz	$(0.005 + 0.002 \times \text{Frequency [kHz]} + K_c) / Z_x[\Omega]$
10kHz < Frequency ≤ 100kHz	$(0.0025 \times \text{Frequency [kHz]} + K_c) / Z_x[\Omega]$

Cable length coefficient  $K_c = 0.001 \times \text{Frequency [kHz]} \times (\text{Cable length [m]})^2$

Use the next table when all of two conditions listed below are satisfied. In this case, unless  $A_z$  exceeds 10 [%], the measurement accuracy is not a supplementary value but a guaranteed value.

Measurement range  $Z_x$  is 10Ω.

Impedance magnitude  $|Z|$  is less than 0.45Ω.

Frequency	K <sub>z</sub> [%]
DC (0Hz), Frequency ≤ 10kHz	$(0.05 + K_c) / Z_x[\Omega]$
10kHz < Frequency ≤ 100kHz	$(0.1 + 0.002 \times \text{Frequency [kHz]} + K_c) / Z_x[\Omega]$

• **K<sub>y</sub>: Residual admittance coefficient**

Frequency	K <sub>y</sub> [%]
DC, Frequency ≤ 120Hz	$Z_x[\Omega] / (3 \times 10^8)$
120Hz < Frequency ≤ 100kHz	$Z_x[\Omega] \times \text{Frequency [kHz]} / (3 \times 10^7)$

• **K<sub>T</sub>: Temperature-dependent coefficient**

Ambient temperature (T °C)	K <sub>T</sub>
0 to +18	$1 + 0.1 \times (18 - T)$
+18 to +28	1
+28 to +40	$1 + 0.1 \times (T - 28)$

• **K<sub>B</sub>: DC bias coefficient**

Internal DC bias	Measurement range Z <sub>r</sub>	K <sub>B</sub> [%]		
		Frequency ≤ 1kHz	1kHz < Frequency ≤ 10kHz	Frequency > 10kHz
Disabled	All ranges	0	0	0
Enabled (*1)	1MΩ	0.005	0.02	0.02
	100kΩ	0.002	0.003	0.01
	100Ω to 10kΩ	0.001	0.002	0.01
	10Ω	0.01	0.01	0.02
	100mΩ, 1Ω	0.05	0.1	0.2

\*1: when open compensation and short compensation are performed at the conditions of internal DC bias enabled and the bias voltage 0V

At all times,  $K_B = 0$  for the direct-current resistance R<sub>dc</sub>.

- **A (upper row): Basic coefficient [%]**
- **B (lower row): Proportional coefficient [%]**

Meas. speed	Meas. range Zr	Measurement frequency Hz								
		0 (DC)	99.999 ↑ 1m	999.99 ↑ 100	1k	1.9884k ↑ 1.0001k	10k ↑ 1.9885k	20k ↑ 10.001k	50k ↑ 20.001k	100k ↑ 50.001k
MED, SLOW, VSLO	1MΩ	0.14 0.02	0.50 0.30	0.15 0.025	0.10 0.02	0.15 0.03	0.25 0.03	0.25 0.03	—	—
	100kΩ	0.12 0.01	0.25 0.04	0.15 0.02	0.09 0.01	0.10 0.015	0.20 0.025	0.25 0.03	0.30 0.03	0.80 0.03
	10kΩ	0.09 0.01	0.20 0.03	0.15 0.02	0.07 0.01	0.09 0.01	0.16 0.015	0.20 0.02	0.25 0.03	0.80 0.03
	1kΩ	0.09 0.01	0.20 0.03	0.15 0.02	0.07 0.01	0.09 0.01	0.16 0.015	0.20 0.02	0.25 0.03	0.30 0.03
	100Ω	0.09 0.01	0.20 0.03	0.15 0.02	0.07 0.01	0.09 0.01	0.16 0.015	0.20 0.02	0.25 0.03	0.30 0.03
	10Ω	0.12 0.02	0.25 0.03	0.17 0.02	0.12 0.01	0.15 0.015	0.20 0.017	0.40 0.03	0.45 0.05	0.50 0.06
	1Ω	0.14 0.05	0.40 0.06	0.30 0.02	0.20 0.02	0.25 0.02	0.35 0.02	0.60 0.03	0.70 0.08	0.90 0.10
	100mΩ	0.14 0.30	0.60 0.40	0.30 0.10	0.30 0.04	0.30 0.04	0.40 0.03	0.60 0.06	0.90 0.10	0.90 0.10
FAST	1MΩ	Same as above	0.50 0.30	0.15 0.025	0.12 0.03	0.15 0.03	0.25 0.03	0.25 0.03	—	—
	100kΩ		0.25 0.04	0.15 0.02	0.09 0.01	0.10 0.015	0.20 0.025	0.25 0.03	0.30 0.03	0.80 0.03
	10kΩ		0.20 0.03	0.15 0.02	0.08 0.01	0.09 0.01	0.16 0.015	0.20 0.02	0.25 0.03	0.80 0.03
	1kΩ		0.20 0.03	0.15 0.02	0.08 0.01	0.09 0.01	0.16 0.015	0.20 0.02	0.25 0.03	0.30 0.03
	100Ω		0.20 0.03	0.15 0.02	0.08 0.01	0.09 0.01	0.16 0.015	0.20 0.03	0.25 0.03	0.30 0.03
	10Ω		0.25 0.03	0.17 0.02	0.13 0.015	0.15 0.02	0.20 0.02	0.40 0.08	0.45 0.08	0.50 0.08
	1Ω		0.40 0.06	0.30 0.02	0.22 0.025	0.25 0.03	0.35 0.03	0.60 0.20	0.70 0.20	0.90 0.20
	100mΩ		0.60 0.40	0.30 0.15	0.30 0.06	0.30 0.06	0.40 0.06	0.80 0.80	1.0 0.80	1.0 0.80
RAP	—	Same as above	For measurement frequency > 250Hz, multiply FAST value by 1.3. For measurement frequency ≤ 250Hz, use FAST value.							

### • Other conditions

Warm-up	30 minutes or more
Zero correction	Execute open correction and short correction.
Cable length correction	Execute according to the cable length.
Measurement accuracy is not guaranteed in a range other than the following applicable frequency range.	

Cable	Applicable frequency range
0m, 1m	All ranges including DC
2m	DC, Frequency $\leq 20\text{kHz}$
4m	DC, Frequency $\leq 1\text{kHz}$

Calibration cycle 1 year

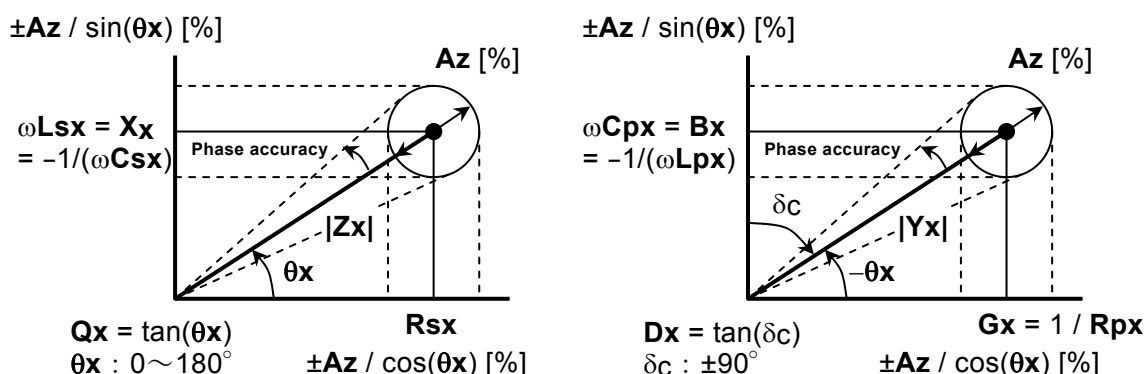
### • Measurement accuracy of measurement parameters except Z and $\theta$

From the measurement accuracy of impedance, obtain as follows.

Here,  $Q_x$  is a measured value of  $Q$ ,  $D_x$  is a measured value of  $D$ , and  $\theta_x$  is a measured value of  $\theta$ .  $\theta_x$  used for accuracy calculation may be obtained from  $(90^\circ - \tan^{-1} |1/Q_x|)$  or  $(90^\circ - \tan^{-1} |D_x|)$ .

Parameter	Measurement accuracy
$ Y $	$\pm A_z$ [%]
$L_p, L_s, X$	$\pm A_z$ [%] ( $ Q_x  \geq 10$ ), $\pm A_z / \sin \theta_x$ [%] ( $ Q_x  < 10$ )
$C_p, C_s, B$	$\pm A_z$ [%] ( $ D_x  \leq 0.1$ ), $\pm A_z / \sin \theta_x$ [%] ( $ D_x  > 0.1$ )
$R_p, R_s, G$	$\pm A_z$ [%] ( $ Q_x  \leq 0.1$ ), $\pm A_z / \cos \theta_x$ [%] ( $ Q_x  > 0.1$ )
$R_{dc}$	$\pm A_z$ [%]
$Q$	$\pm Q_x^2 \times P_e / (1 -  Q_x  \times P_e)$ ( $ Q_x  \geq 10$ , $ Q_x  \times P_e \leq 0.1$ ) Here, the phase angle error $P_e$ [rad] = $0.01 \times A_z$ [%]. It differs from $P_z$ [°]. Measurement accuracy of $Q$ is absolute value. It is not a % value.
$D$	$\pm (0.01 \times A_z)$ ( $ D_x  \leq 0.1$ ) Measurement accuracy of $D$ is absolute value. It is not a % value.

In general, a range of each measurement parameter (maximum value and minimum value) can be calculated based on an error circle of the impedance.



$\omega = 2 \times \pi \times \text{Measurement frequency [Hz]}$ , Suffix “x” of the parameter indicates a measured value.

Figure 1-1 Range of error

Pure L [H] and C [F] can be converted into  $|Z|$  [ $\Omega$ ] by the following expression:

$$|Z| [\Omega] = 2 \times \pi \times \text{Frequency [Hz]} \times L [\text{H}]$$

$$|Z| [\Omega] = 1 / (2 \times \pi \times \text{Frequency [Hz]} \times C [\text{F}])$$

Approximate value can be read from the following graph.

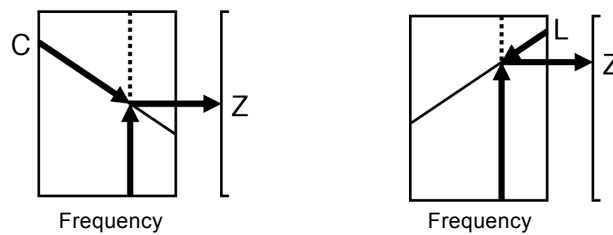
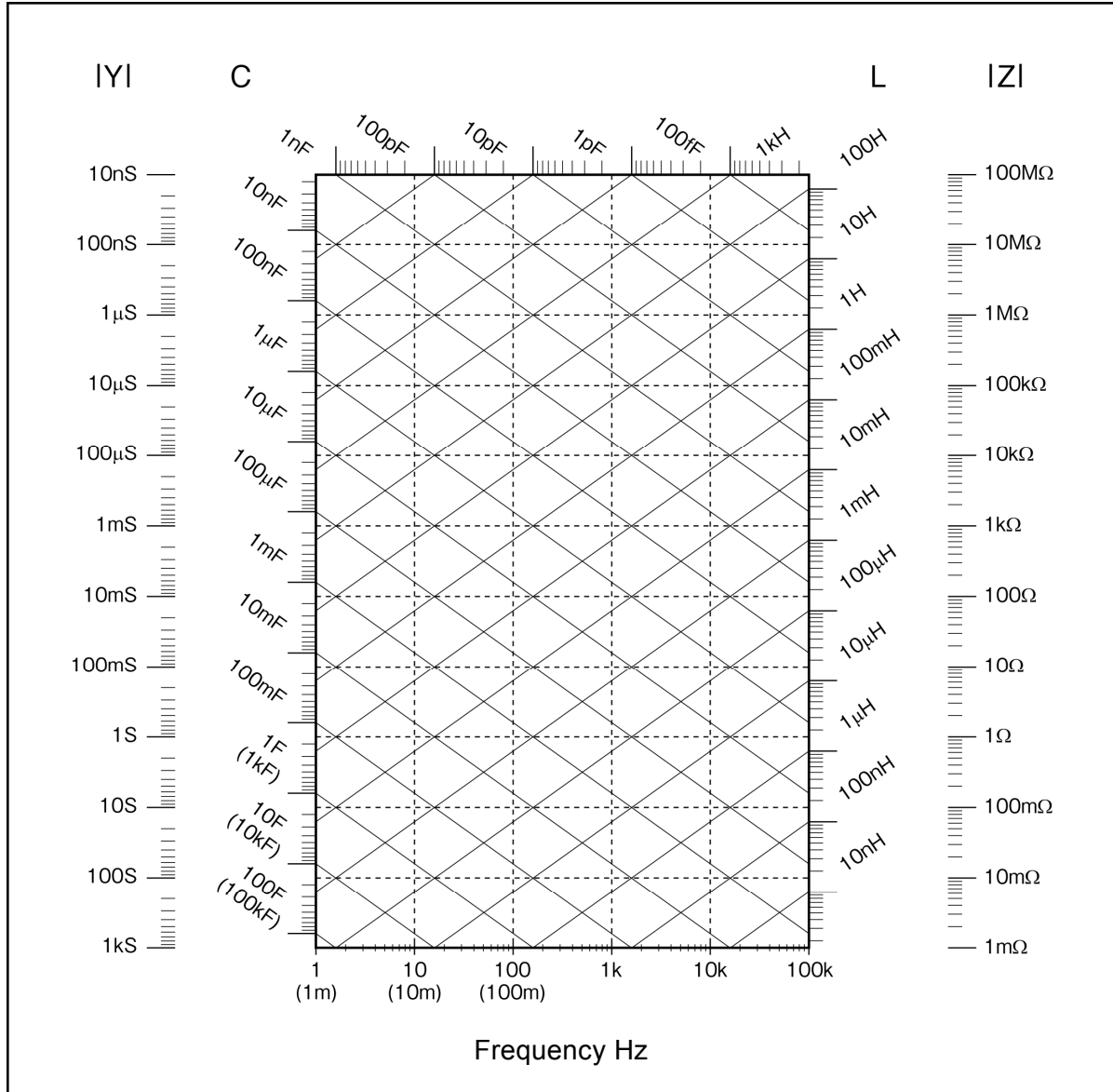


Figure 1-2 LC - Z conversion graph



## Other measurement related functions

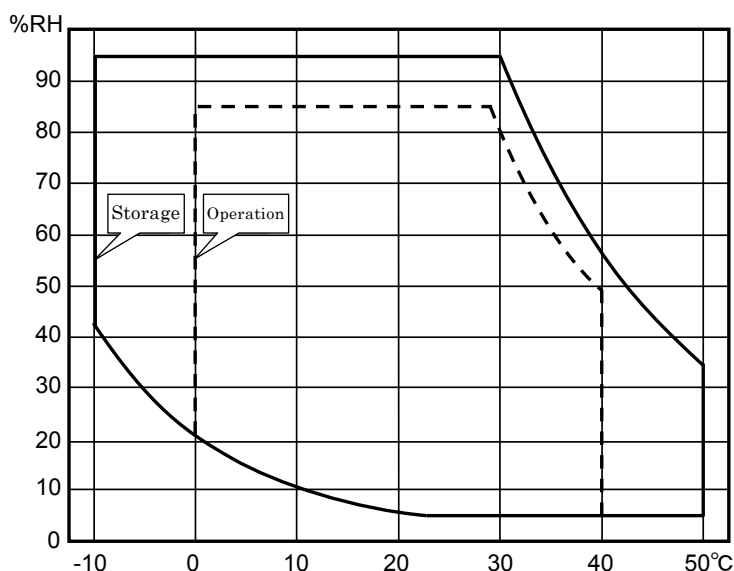
- Zero correction Open correction and short correction provided. Both can be turned on or off.
- Load correction Provided. It can be turned on or off.
- Cable length correction 0m / 1m / 2m / 4m
- Contact check (Standard for **ZM2372**. Not provided for **ZM2371**)  
For all 4 terminals, a contact failure to DUT is detected.  
Additional time 4ms (supplementary value)
- Averaging 1 to 256 times
- Deviation measurement Primary parameters: Deviation and deviation % from reference value can be displayed.  
Secondary parameters: Deviation and deviation % from reference value can be displayed.
- Comparator Primary parameters: Max. 9 bins (**ZM2371**) / Max. 14 bins (**ZM2372**)  
Original measured value / Deviation / Deviation % can be sorted.  
Secondary parameters: Upper limit and lower limit comparison  
Original measured value / Deviation / Deviation % can be sorted.  
Beeper: Sounds according to comparator result (Pass / Fail / Off)
- Handler interface (Standard for **ZM2372**. Not provided for **ZM2371**)  
Signal isolation: All I/O signals are optically isolated (withstand voltage  $\pm 42\text{V}$ )  
Input signals: Trigger, Key lock, Settings/correction value memory designation  
Output signals: Comparator result BIN1 to BIN11, NC / BIN12, PHI / BIN13, PLO / BIN14, OUT OF BINS, S-NG, ERR, INDEX, EOM (NC, PHI, and PLO cannot be used when BIN10 - BIN14 are used)  
Rated power voltage: External +5V to +24V,  
Internal +5V (non- isolated)
- Monitor display Voltage: Voltage value applied to the DUT  
Voltage monitor accuracy  $\pm(2\%+2\text{mVrms})$  10Hz to 50kHz  
 $\pm(3.5\%+2\text{mVrms})$  50kHz <  
Current: Current value flowing in the DUT  
Current monitor accuracy (supplementary value)  
Voltage monitor accuracy + Measurement accuracy of impedance Z
- Discharge protection 8J or less when voltage is below 250V, or 1J or less when below 1kV.  
However, for output impedance  $5\Omega$ , below 250V and 2J or less.  
(All are supplementary values)

### ■ Remote control interface

- USB USBTMC, USB 1.1 full speed
- RS-232
  - Data rate  
4800 / 9600 / 19200 / 38400 / 57600 / 115200 / 230400bps  
For the data rate exceeding 19200bps, communication may fail  
depending on the characteristics of cable or controller.
  - Flow control  
None, Software (X-ON/X-OFF), Hardware (RTS/CTS)
- GPIB (standard for **ZM2372**. Not provided for **ZM2371**)  
Conforms to IEEE 488.1 and IEEE 488.2 Standards

## ■ General specifications

- Power supply
  - Voltage: AC 100V to 230V  $\pm 10\%$ , but 250V or less
  - Frequency: 50Hz/60Hz  $\pm 2\text{Hz}$
  - Power consumption: 70VA or less (**ZM2371**),  
75VA or less (**ZM2372**)
  - Over voltage category II
- Environmental conditions
  - Operation
    - Temperature: 0 to  $+40^{\circ}\text{C}$
    - Humidity: 5 to 85%RH Absolute humidity 1 to  $25\text{g/m}^3$ ,  
non-condensing
    - Altitude: 2000m or less
  - Storage
    - Temperature:  $-10$  to  $+50^{\circ}\text{C}$
    - Humidity: 5 to 95%RH Absolute humidity 1 to  $29\text{g/m}^3$ ,  
non-condensing



- Warm-up time 30 minutes
- Settings/correction value memory 32 sets. Settings and correction values can be saved and restore individually or together.
- Resume Last setting and correction value are restore when power is turned on.
- Safety regulation EN 61010-1 (Pollution degree: 2)  
EN 61010-2-030
- EMC EN 61326-1 (Group 1, Class A)  
EN 61000-3-2  
EN 61000-3-3
- RoHS Directive 2011/65/EU
- External dimensions Approx. 260 (W)  $\times$  88 (H)  $\times$  220 (D) mm, not including protuberances
- Weight Approx. 2.0kg (**ZM2371**), approx. 2.1kg (**ZM2372**) (not including accessories)

## 1.2 External Dimensions

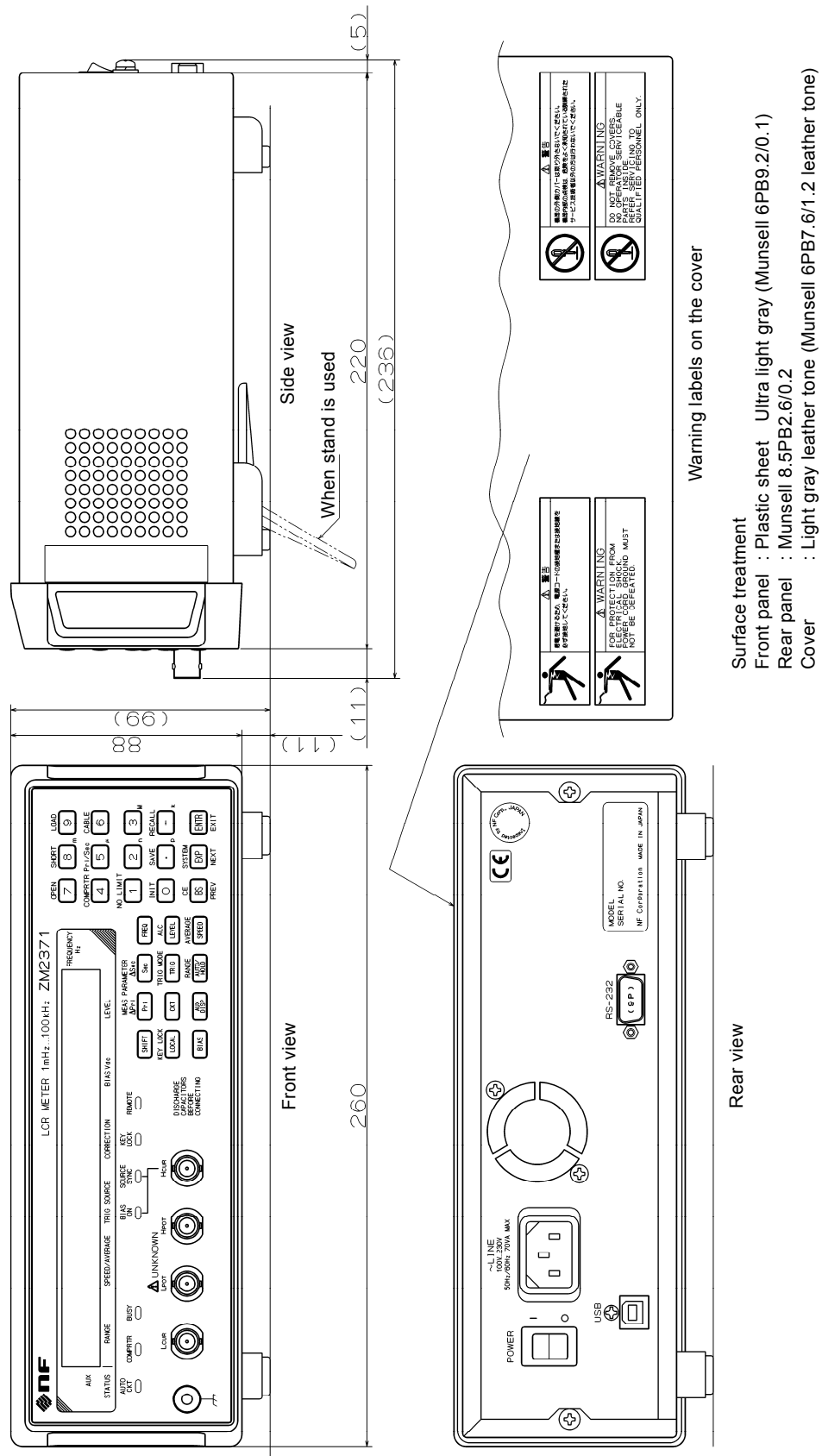


Figure 1-3 ZM2371 External dimensions

## 1.2 External Dimensions

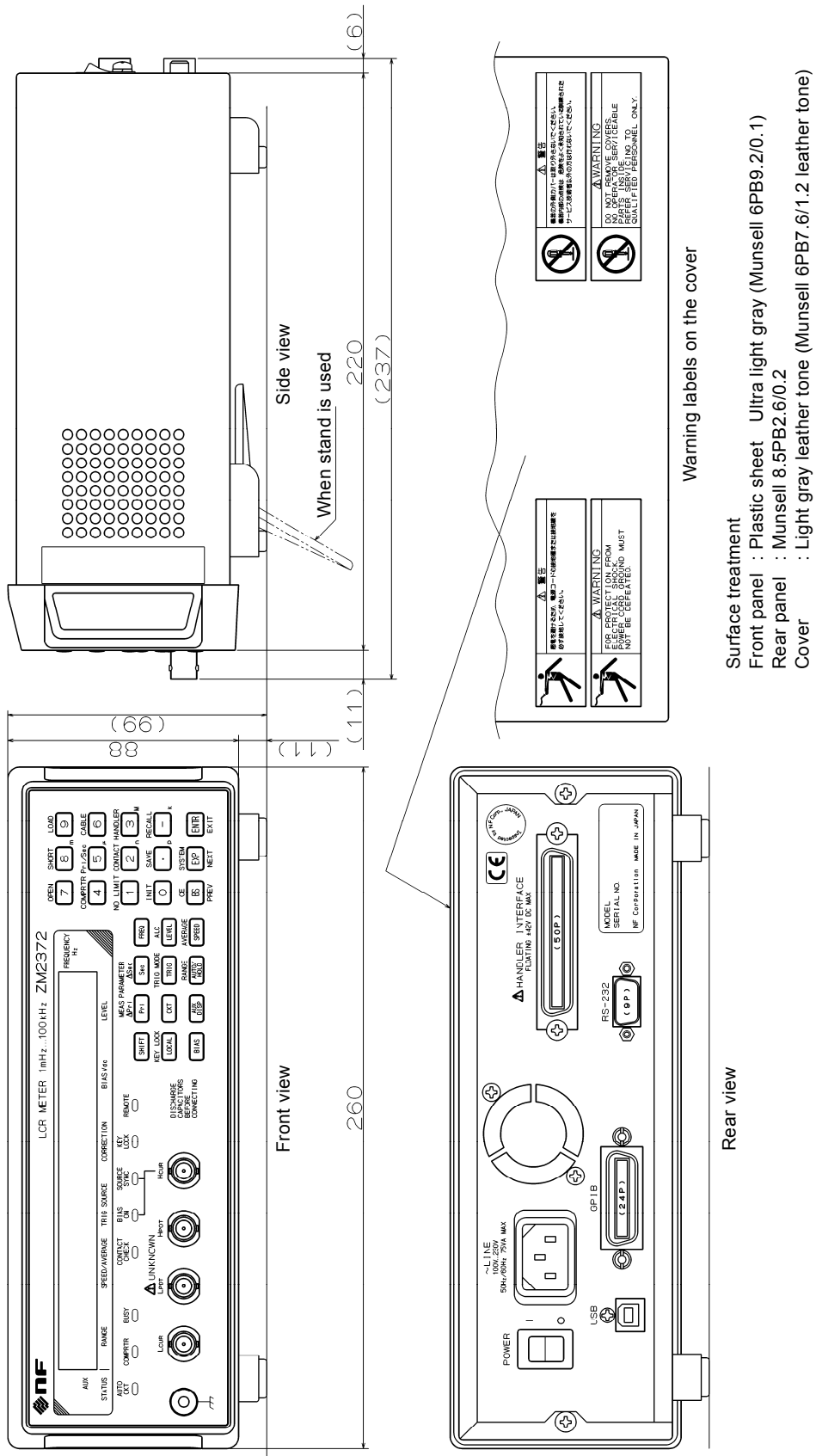


Figure 1-4 ZM2372 External dimensions



# WARRANTY

NF Corporation certifies that the **ZM2371 / ZM2372** was thoroughly tested and inspected when it was shipped from our factory.

If any failures attributable to defects in material and workmanship or accidents during transportation are found, please get in touch with NF Corporation or one of our representatives.

For the product purchased from NF Corporation or one of our representatives, any failures found to be caused by NF Corporation's responsibility such as parts failures that occurred under normal operating conditions or defects in material and workmanship shall be covered by the warranty for one year after the date of delivery. NF Corporation will repair such defective product free of charge, if the purchaser contacts NF Corporation or one of our representatives within the warranty period. This warranty is valid only in Japan. When the product is to be used outside Japan, please consult NF Corporation or one of our representatives.

Repair of defective product that occurred by either of the following causes shall be charged even within the warranty period.

- Failure due to the handling or storage that violates the operating methods or precautions given in the instruction manual
- Failure or damage caused by a fall or shock during transportation or relocation performed by the purchaser
- Modification made to the product by the purchaser
- Failure by external abnormal voltage or influence of external equipment connected to the product
- Failure or damage caused by fire, earthquake, flood, thunder, rebellion, war, and force majeure including other act of providence.
- Replenishment of consumable parts such as magnetic tapes and batteries

# REPAIR

When a failure occurred and the product was found to be defective or you have any uncertainty, please get in touch with NF Corporation or one of our representatives. In such a case, let us know the model name (or product name), serial number (SERIAL No. given on the nameplate), and symptom and operating conditions as detail as possible.

Though we will make efforts to reduce the repair period, when five or more years have passed since you purchased the product, it may take time due to, for instance, the out of stock of repair parts.

Also, if the production of repair parts is discontinued, the product is extremely damaged, or the product is modified, we may decline the repair.





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## NOTES

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- Reproduction of the instruction manual, part or whole, is forbidden without prior written permission.
- The contents of the instruction manual are subject to change without notice.
- Information provided in the instruction manual is intended to be accurate and reliable. However, we assume no responsibility for any damage regarding the contents of the instruction manual.

If you have any uncertainty or you found an error or omission, please contact NF Corporation or one of our representatives from which you purchased the product.

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## **ZM2371 / ZM2372    Instruction Manual**

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